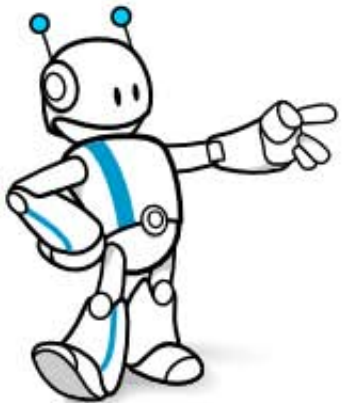
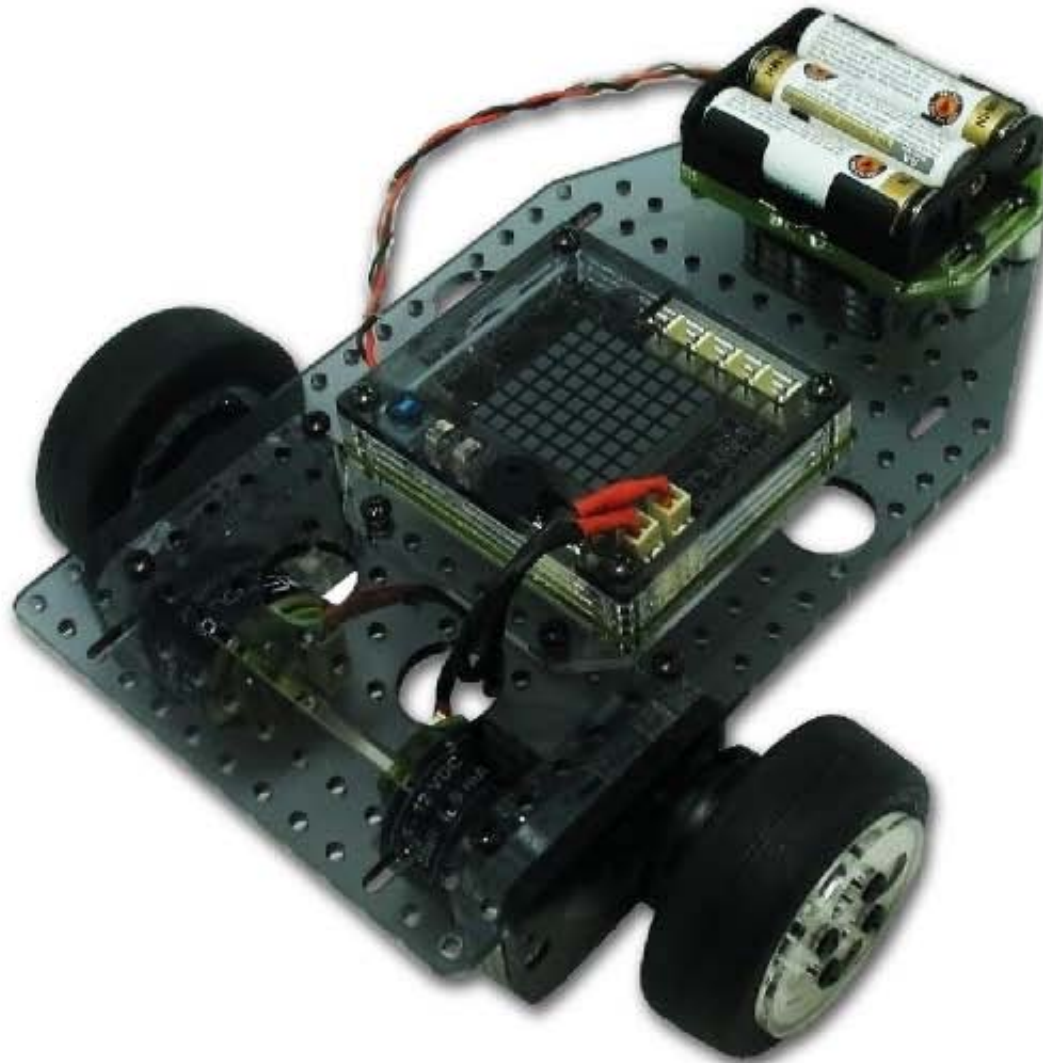



# Secuencia de armado de tu primer robot




1

1x




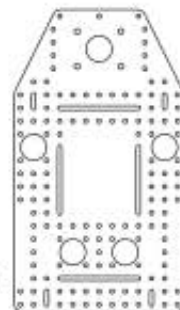
2

4x



4x


 (20mm)




1x


3

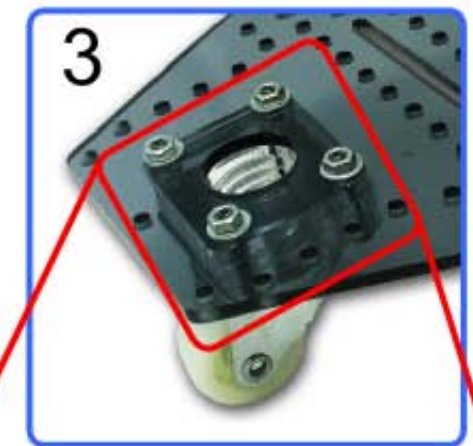
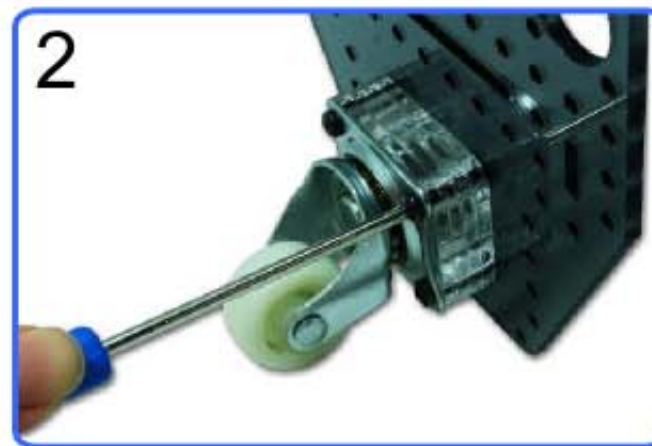
4x



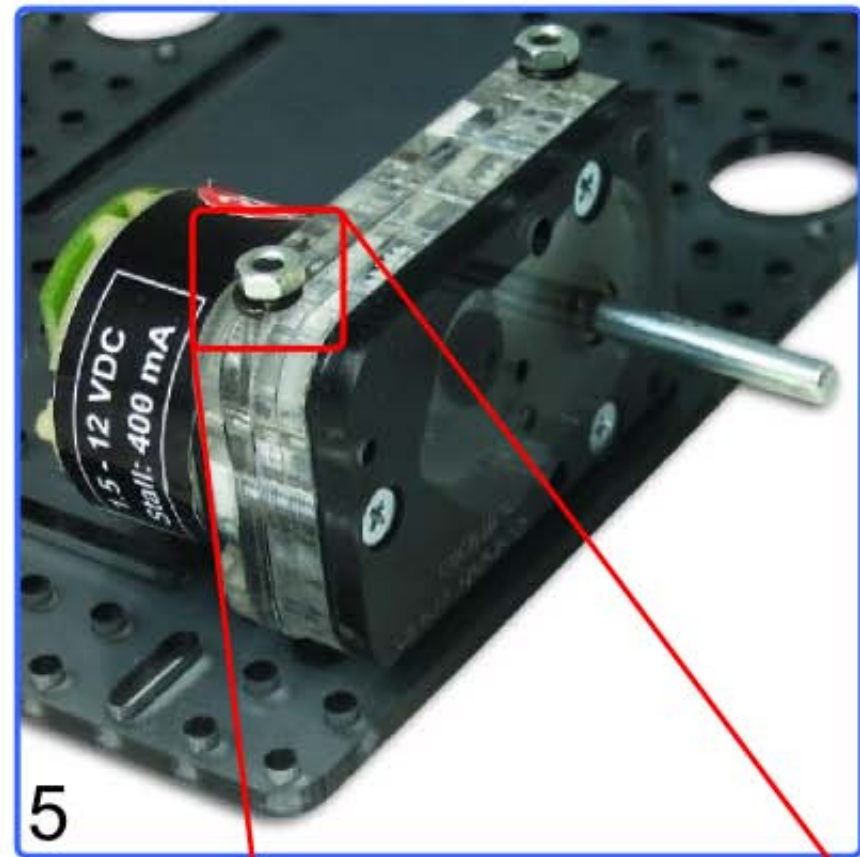
4x




















- 8
- 1x 
  - 1x  (24mm)
  - 1x 
  - 1x 
  - 1x 

- 9
- 2x  (24mm)
  - 2x 
  - 2x 
  - 2x 

